



IDP Computer Vision

TUM Interdisciplinary Project

Angsa revolutionizes the removal of trash on grass and gravel: Individual objects are detected by an artificial intelligence and removed by the autonomous robot.



Who we are looking for

- You like solving complex problems!
- Proficiency in Python and/or C++
- Structured coding style & teamwork
- Experience form previous projects

You will become owner of your submodule: All the way from design, build-up to testing.



Possible Tasks

- Data: Synthetic data generation using LLMs
- Modeling: Improve real-time performance on tensor-optimized deep learning chips
- Vision Pipeline: End-to-end optimization of deep learning inference

3 What we offer

- Real-world impact: Your modules are used with pilot customers in multiple cities.
- Responsibility and Leadership: Good work and ownership are rewarded at Angsa: You can play a decisive role in shaping your role in the team.
- Workplace & Equipment: A workplace with desk for you in our office and workshop in the Munich Urban Colab, access to the Makerspace, free coffee & snacks.

Sounds Interesting?

Email us your profile and indicate if you are interested in joining Angsa as a working student after the IDP.

Find us in the city center: Münchner Gewerbehöfe Your Contact: Karl Schulz jobs@angsa-robotics.com